Searching for ring-like structures in the cosmic microwave background

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ABSTRACT

In this research, we present an alternative methodology to search for ring-like structures in the sky with unusually large temperature gradients, namely, Hawking points (HPs), in the Cosmic Microwave Background (CMB), which are possible observational effects associated with Conformal Cyclic Cosmology (CCC). To assess the performance of our method, we constructed an artificial data set of HP, according to CCC, and we were able to retrieve 95 per cent of ring-like anomalies from it. Furthermore, we scanned the *Planck* CMB sky map and compared it to simulations according to ΛCDM , where we applied robust statistical tests to assess the existence of HP. Even though no significant ring-like structures were observed, we report the largest excess of HP candidates found at $\alpha = 1$ per cent significance level for the analysed sky maps (CMB at 70GHz, SEVEM, SMICA, and Commander-Ruler), and we stress the need to continue the theoretical and experimental research in this direction.

Key words: methods: statistical - early Universe - cosmic background radiation.

1 INTRODUCTION

Numerous theories have been proposed and several experiments have been performed to answer one of the most fundamental questions of humanity: what are the dynamics of the very early and very late universe? The resulting answer involves the Standard Cosmological Model, ΛCDM , although there are some inconsistencies with other areas of Physics that some speculative theories try to solve [see discussion in Penrose (2004)]. In this research we explore the observational implications in the Cosmic Microwave Background (CMB) of a theory of Sir Roger Penrose named Conformal Cyclic Cosmology (CCC) Penrose (2010), whose latest statistical analyses have been under discussion, An et al. (2020), Jow & Scott (2020). Moreover, we develop a method to assess its presence and potential location in the CMB.

The main premise of CCC is that the universe is in a state of eternal inflation and its full evolution is divided in *aeons* that are separated from each other by conformal transformations at the *crossover* (Penrose 2004, 2010). In a remote future all matter will either be captured in supermassive black holes, that subsequently radiate into mass-less particles by *Hawking evaporation*, or, as it is postulated by CCC, will experience a mass fade out to become mass-less with time (see An et al. (2020) for details). Eventually, this remote and mass-less universe will be conformally indistinguishable from the start of a new universe. Penrose argues that this resemblance is not coincidental and as such, the end of a universe can be mapped to the beginning of a new universe, making the history of the universe a (possibly endless) cycle of *aeons*.

Similarly to ΛCDM , every *aeon* described by CCC starts with a Big Bang and, due to the cosmological constant $\Lambda > 0$, ends with an exponential expansion in a remote future around $\sim 10^{100}$ years. The main differences between ΛCDM and CCC are that Penrose does not consider a model with early universe *inflation* and that the entire history of the universe is taken to be a succession of *aeons*. In CCC, an *aeon* is defined as the start of the universe and the end of it.

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According to CCC, there are two types of events from the previous *aeon* that could be observed in the present universe. One of these would be the effects of gravitational waves coming from inspiralling pairs of supermassive black holes and the other the effects of the evaporation of supermassive black holes, known as *Hawking points* (hereafter '*HPs*'). In this research, we will focus our attention on the second type of event.

At the end of an *aeon*, mass-less particles are *squashed conformally* at the cross-over. Hence, all radiation from the evaporation of a black hole is concentrated into an HP, and it will travel into the subsequent *aeon* 'heating' the matter of the early Universe, leaving imprints in the Cosmic Microwave Background (CMB). Due to relativistic constraints and given the known expansion of the universe, the imprints are expected in the form of a *Gaussianlike* distribution, projected in the CMB as circular annuli that do not exceed an outer diameter of $\sim 4^{\circ}$, corresponding to a maximum outer radius of ~ 0.035 radians An et al. (2020). There is also an inner radius of the annuli since the supermassive black hole will have evaporated before the cross-over takes place. The size of this inner radius depends on how much time has passed between evaporation has been completed and the cross-over, and cannot be determined *a priori*.

To accept or reject CCC it is crucial to perform robust analyses on the data from the CMB to verify the existence of HP and their

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Published by Oxford University Press on behalf of Royal Astronomical Society. This is an Open Access article distributed under the terms of the Creative Commons Attribution License (https://creativecommons.org/licenses/by/4.0/), which permits unrestricted reuse, distribution, and reproduction in any medium, provided the original work is properly cited. locations in the sky. This study aims to search for anomalous annuli in the CMB temperature field data by comparing two different distributions: one population where HPs could potentially exist and another population where HPs are not present. The first population comes from the CMB sky map measured by *Planck* (hereafter *real CMB sky map*), whereas the second population is obtained via simulations according to the Standard Cosmological theory ΛCDM (hereafter *simulated CMB sky map*).

This paper is organized as follows. A brief overview of related works is given in Section 2. In Section 3 we describe the real data and the simulations of the CMB temperature field. Subsequently, we define our measurements (Section 4.1), we provide a pseudo-code of the algorithm to scan the CMB sky maps (Section 4.2) and we describe the methodology employed to measure the quality of the simulations, the existence of HPs and their locations (Sections 4.3, 4.4, and 4.5). In Section 5 we report the results and show the performance of our procedure. Finally, in Section 6 we discuss our results and provide some conclusions.

2 RELATED WORK: IMPRINTS OF THE PREVIOUS AEON

Several studies aiming at testing CCC have been conducted since Penrose presented his theory. Most of these studies aimed to indirectly detect gravitational waves produced by the collision of supermassive black holes in the previous aeon. It is theorized that collisions and formations of supermassive black holes would happen in the same galaxies due to the abundance of matter. As a consequence of several mergers in the same region, those remnants from the previous *aeon* should be projected in the CMB as concentric rings with an angular diameter $\leq 40^{\circ}$. Although this type of event is not discussed in this study, we can extrapolate some search methodologies from it, and therefore we briefly describe them below.

In Gurzadyan & Penrose (2010), the authors explore Wilkinson Microwave Anisotropy Probe (WMAP) data to search for rings with low-temperature variance according to a certain threshold and large populations of annuli were encountered in some regions. The points selected in the CMB were centres of concentric rings and deviated 6σ along the annuli from the Gaussian expectation of Λ *CDM*. In Gurzadyan & Penrose (2013), it was proposed the *sky*-*twist* methodology to test whether the numerous centres of multiple low-variance rings depended upon them being circular rather than some other shape, as the existence of elliptical shapes in WMAP sky map would contradict CCC. However, it was observed that low-variance ellipses were nonexistent in the data.

In Meissner, Nurowski & Ruszczycki (2013) three different frequency bands with artificial Gaussian maps with the same harmonic spectrum were scanned and their results compared, whereas in An, Meissner & Nurowski (2018) the same study was carried out by using Planck data. The comparison was performed by means of a methodology proposed in Meissner (2012), known as *A*-functions (also presented in Section 4.3). Due to a high computational cost only 100 statistical artificial maps were scanned and the authors found ring-like structures with 99.7 per cent confidence level.

In DeAbreu, Contreras & Scott (2015), the analysis of Gurzadyan & Penrose (2010) with WMAP and Planck data was repeated. The authors performed the same procedure not only on real maps, but also on sky maps sampled from Gaussian distributions containing the usual CMB anisotropy power spectrum, which is consistent with the predictions of ΛCDM , and the same results were obtained for both types of maps. Moreover, it is argued that the threshold chosen

to select the low-variance rings in Gurzadyan & Penrose (2010) was a particular search criterion and had no statistical significance.

In Wehus & Eriksen (2011) the same analysis as in Meissner et al. (2013) was implemented, but instead of employing the A-functions to compare the real distribution against an artificial distribution, the authors developed a methodology based on matched filters and χ^2 statistics to compare both distributions. Due to their results, the authors concluded that no imprints were present in the data.

Regarding studies that aimed to detect HPs, in An et al. (2020), after scanning a real CMB sky map and 10 000 simulated maps, the authors claimed to have found HPs in the real sky map at 99.98 per cent confidence level according to the metrics of Meissner (2012), in favour of CCC. In Jow & Scott (2020), the authors reported to have found HPs at 87 per cent confidence level with the same metrics, concluding that this result is not significant enough. It is important to note that both studies employed large sky maps of N_{side} = 1024, where this parameter represents the resolution of the grid used according to Healpy (Gorski et al. 1999).

3 THE COSMIC MICROWAVE BACKGROUND TEMPERATURE FIELD

The CMB offers us a look at the universe when it was about 1/36 000 of its present age. At that time, the universe became transparent, emitting photons that have travelled freely ever since. However, not all photons that arrive at our antennas belong to the CMB. The main astrophysical sources of noise come from our Galaxy through different mechanisms: synchrotron radiation, free-free emission, and spinning dust radiation, which dominates at low frequencies, and thermal dust, which dominates at higher frequencies. At 70 GHz, the contribution of sources of noise is smaller (An et al. 2020), but there are still systematic errors in the CMB temperature determination that are not taken into account. For these reasons, many cleaning techniques had been developed to remove the foregrounds from the sky maps obtained from telescopes, such as Spectral Estimation Via Expectation-Maximization (SEVEM), Spectral Matching Independent Component Analysis (SMICA), and Commander - Ruler (Ade et al. 2014a). In the present work, we employ the full missions maps cleaned from *Planck* 2nd release,¹ as well as the CMB sky map at 70 GHz, and we refer to them as the real CMB sky maps.

As we mentioned before, we aim to compare a population where HPs are potentially present, namely the real CMB sky maps, with a population where HPs are guaranteed to not exist, i.e. simulated CMB sky maps following ΛCDM , to later compute their similarities or dissimilarities. Simulating the CMB temperature field is nontrivial, as this radiation encloses a large amount of information about the primordial Universe, which is strongly dependent on its shape and early composition. Fortunately, we can artificially obtain CMB sky maps with the Code for Anisotropies in the Microwave Background (CAMB) (Howlett et al. 2012; Lewis, Challinor & Lasenby 2000). With CAMB we can compute the angular power spectrum of the simulation $C_{\ell_{sim}}$ according to the cosmological parameters obtained from Planck 2018 (Aghanim et al. 2020), and with *Healpy* a temperature field is generated. From the possible values that multipole ℓ could acquire, we exclude ℓ_0 and ℓ_1 and we only expand the CMB until $\ell = 1500$, which is expected to have a negligible effect on the temperature, as proposed in (An et al. 2020).

¹They can be downloaded from Infrared Science Archive on Planck Public Data Release 2 https://irsa.ipac.caltech.edu/data/Planck/release_2/all-sky-m aps/matrix_cmb.html

Due to the resolution of our maps being $N_{\text{side}} = 1024$, to simulate Planck's camera resolution we smooth $C_{\ell_{\text{sim}}}$ with a Gaussian beam at *fwhm* = 10[′] according to Ade et al. (2014b) with *Healpy* package (Zonca et al. 2019; Górski et al. 2005).

Because we are interested in testing the existence and the location of HPs in many simulated maps, we computed several artificial maps coming from the same angular power spectrum with *Healpy*. The code that generates the simulated maps needs to distribute the temperature field following ΛCDM , with the assumption that the CMB sky map is almost a Gaussian distribution. As the distribution occurs with a random seed, no two maps are alike and we can simulate the artificial maps recursively.

4 THE METHODOLOGY

We propose a methodology to find ring-like anisotropies in the CMB. For this aim we compare two distributions of measurements: one where HPs could potentially exist (real CMB sky maps) and another one where they are not present (simulated CMB sky maps in accordance to Λ *CDM*). To construct both distributions we need to scan all the different sky maps from Section 3 and calculate specific metrics at each pre-defined sky location for annuli of different inner and outer radius { r_{in} , r_{out} }. In this study, we employed two metrics: normalized slope and Pearson correlation coefficient (both introduced in Section 4.1).

Once we have computed all values for a metric, we perform statistical tests to understand if temperature fluctuations are expected by ΛCDM or are anomalies in accordance to CCC. For this, we measure the similarity or dissimilarity of both distributions of a metric, in the region where HPs are expected according to CCC, $(r_{out} \leq 0.035 \text{ rad})$. Another crucial point is to assess the reliability of the simulations, i.e. we need to compare both distributions in the region where HPs are not expected under the assumption that they are similar ($r_{out} \geq 0.035 \text{ rad}$). Finally, if HPs were to be found in the real CMB sky maps, we would locate them to compare them against the ones found in An et al. (2020).

This section is structured as follows: we provide a definition of the two metrics employed in 4.1, and we present a pseudo-code of the scanning algorithm in 4.2. In 4.3 we give an overview of the statistical tests employed, and the underlying hypotheses. In Section 4.4 we present a methodology to compute the locations of HPs in the real CMB sky map, if we were to find evidences of their existence. Finally, in Section 4.5 we assess performance of the algorithm with an artificial data set.

4.1 Measuring the slope

According to CCC, HPs present a Gaussian-like distribution, but in the real CMB sky map they would be projected as two-dimensional (2D) annuli, whose temperature gradient monotonically decreases as we move away from the centre. Around the region where the temperature gradient is maximum we can approximate T(d) to depend linearly on the angular distance d, in the local neighborhood of the maximum gradient of T(d). With this idea in mind, several authors searched for negative slopes of the temperature around given sky directions [see An et al. (2020) and Jow & Scott (2020) for details]. HPs should show the most negative normalized slopes of the population, but it is not known *how much negative*.

To find such slopes, we can employ common least squares, where we define *a* as the slope of the linear relationship and *b* as the intercept of the line T = ad + b. Because we intend to scan the CMB sky maps to search for annuli of different sizes $\{r_{in}, r_{out}\}$, one needs to keep in mind that a change in size implies a change in the number of pixels and hence different variances for the slope. To take this into account, in An et al. (2020) the authors define the measurement needed to search for HPs as the normalized slope, i.e. $\hat{a} = a/\sigma_a$, where σ_a is the standard deviation of the distribution of measured slopes of all annuli of the same size present in the sky map. In this research we also use the Pearson correlation coefficient *r* between the angular distance *d* and the temperature *T* as a measurement to search for HPs, because the whole measurement of a HP depends on the assumption that these two variables are linearly correlated.

4.2 Scanning the cosmic microwave background

We scanned 1004 sky maps of ≈ 12.5 million pixels each to search for HP. For this aim, we built a Python code employing *Healpy* and *Numba* packages for efficient computing (Górski et al. 2005; Zonca et al. 2019; Lam, Pitrou & Seibert 2015), and we provide its pseudo-code in Algorithm 1.

Algorithm 1 Computation of measurement m			
Require: Temperature T, c centers, annulus size $\{r_{in}, r_{out}\}$.			
1: Initialise $M = \emptyset$			
2: for all c do			
3: for all $\{r_{in}, r_{out}\}$ do			
4: Get pixels:			
5: $\mathcal{P}(c, r_{\text{in}}, r_{\text{out}}) = \text{masked sky map} \cap \mathcal{A}(c, r_{\text{in}}, r_{\text{out}})$			
6: if $#(\mathcal{A}(c, r_{\text{in}}, r_{\text{out}}) \setminus masked) > 75$ then			
7: Get temperatures $T(\mathcal{P}(c, r_{\text{in}}, r_{\text{out}}))$			
8: Calculate angular distances $d(\mathcal{P}(c, r_{\text{in}}, r_{\text{out}}))$			
9: Calculate the measurement $m(c, r_{in}, r_{out})$			
10: $M = M \cup \{m(c, r_{in}, r_{out})\}$			
11: end if			
12: end for			
13: end for			
14: return M			

The task of Algorithm 1 is to scan a sky map for each pre-defined annulus, defined as

 $\mathcal{A}(c, r_{\rm in}, r_{\rm out}) \equiv \{ x \notin \mathcal{X} \mid r_{\rm in} < |x - c| < r_{\rm out} \},\tag{1}$

for a given center $c = \{l, b\}$, where *l* and *b* represent the galactic longitude and latitude respectively, and a certain inner and outer radius $\{r_{\text{in}}, r_{\text{out}}\}$. Defining the width $\epsilon = r_{out} - r_{\text{in}}$, the range of annuli explored in this research is $\epsilon \in (0.005, 0.03)$ with a step of 0.005 and $r_{\text{in}} \in (0.000, 0.040)$ with a step of 0.025, which is half of the r_{in} step used in An et al. (2020). The motivation behind the choice of these parameter ranges is to have a similar number of sizes where HP are both expected and not expected to be found theoretically.

To avoid undesired contribution of the Galactic Centre we used a Galactic belt mask defined as $\mathcal{X} = \{0 < l < 2\pi, -\frac{\pi}{4} < b < \frac{\pi}{4}\}$, as proposed in An et al. (2020). Furthermore, we also employed pre-defined masks \mathcal{X} of SEVEM, SMICA, and Commander-Ruler, which are more restrictive and cover the undesired contribution from point sources outside of the Milky Way galaxy.

Because different masks \mathcal{X} cover different amount of pixels, we describe in Table 1 the number of pre-defined centres *c* where we compute measurements, which we define as *C*. Due to the large number of sizes explored, we present the minimum, maximum, and mean (μ) of *C*.

Table 1. Number of pre-defined locations (C) explored for each mask.

	$\operatorname{Min}\left(C ight)$	Max(C)	$\mu(C)$
SEVEM	3,182	10,383	7,062
SMICA	2,832	28,7151	13,781
Commander-Ruler	3,645	23,357	13,332
Galactic belt	12,320	12,640	12,487

At each location we obtain the pixels of annuli with different sizes $\{r_{in}, r_{out}\}$ as

$$\mathcal{P}(c, r_{\rm in}, r_{\rm out}) = maskedskymap \cap \mathcal{A}(c, r_{\rm in}, r_{\rm out}).$$
⁽²⁾

Computationally, we obtain the pixels of the inner circle \mathcal{P}_{in} , and the pixels of the outer circle \mathcal{P}_{out} to get the inverse intersection $\mathcal{P}(c, r_{\text{in}}, r_{\text{out}}) = (\mathcal{P}_{in}(c, r_{\text{in}}) \cap \mathcal{P}_{out}(c, r_{\text{out}}))'$. We obtain the temperature of the pixels $T(\mathcal{P}(c, r_{\text{in}}, r_{\text{out}}))$ and the angular distance $d(\mathcal{P}(c, r_{\text{in}}, r_{\text{out}}))$ from the pixels to the centre c.² Finally, we calculate the values of the slope *a* and the Pearson coefficient *r* for each $(c, r_{\text{in}}, r_{\text{out}})$.

We define a family of annuli $\mathscr{A}(r_{\text{in}}, r_{\text{out}})$ to be the set of all annuli with the same size but different centres *c*,

$$\mathscr{A}(r_{\rm in}, r_{\rm out}) \equiv \{ \mathcal{A}(c, r_{\rm in}, r_{\rm out}) \mid \forall c \}, \tag{3}$$

Furthermore, we define $\sigma_a = \sigma(\mathscr{A}(r_{\text{in}}, r_{\text{out}}))$, as the standard deviation of the slopes of all the annuli that belong to the same family. Thus, we normalize the slope *a* as $\hat{a} = a/\sigma_a$ (see Section 4.1 for details).

4.3 Statistical methods for the absence of Hawking points and the reliability of the simulations

In this subsection we present different hypothesis (labeled in Roman numerals) and two statistical methodologies (labeled in Arabic numbers) to search for HPs in the CMB. Once we have calculated the values of the normalized slope \hat{a} and the Pearson coefficient r for each (c, r_{in}, r_{out}) , and for all the real and simulated CMB sky maps, we would like to see what are the similarities between them. Therefore, given a sky map, we define $\mathcal{M}(r_{in}, r_{out})$ to be the set of all the measurements for a fixed size $\{r_{in}, r_{out}\}$ as,

$$\mathscr{M}_{r_{\text{in}},r_{\text{out}}}^{\text{sky map}} = \{m(c, r_{\text{in}}, r_{\text{out}}) \mid c \in \mathbb{R}^2\}$$

$$(4)$$

and we test the similarity of the measurements from the real $(\mathcal{M}_{r_{in,r_{out}}}^{eal})$ and the simulated sky maps $(\mathcal{M}_{r_{in,r_{out}}}^{im})$ in two different cases:

(i) Testing the reliability of simulated CMB sky maps for $r_{out} \ge 0.035$: $\mathscr{M}_{r_{in},r_{out}}^{eal} \sim \mathscr{M}_{r_{in},r_{out}}^{im}$ on average.

For this case and according to CCC, the ring-like structures associated with HPs should not occur in the real CMB sky maps, so a similarity is expected between $\mathcal{M}_{r_{in},r_{out}}^{eal}$ and $\mathcal{M}_{r_{in},r_{out}}^{sim}$, on average, with a *p*-value $p \ge 0.01$. Results of this analysis are reported in Section 5.2.

(ii) Testing the absence of HPs for $r_{out} \leq 0.035 \mathcal{M}_{r_{in},r_{out}}^{real} \geq \mathcal{M}_{r_{in},r_{out}}^{sim}$ on average.

For this regime and according to CCC, HPs should be observable through their associated ring-like structures in the real CMB sky maps. Setting the non-existence of HPs as our null-hypothesis, we expect to find no proof of a larger amount of extreme negative slope measurements in $\mathcal{M}_{r_{in},r_{out}}^{real}$, or that $\mathcal{M}_{r_{in},r_{out}}^{real} \geq \mathcal{M}_{r_{in},r_{out}}^{sim}$ on average with a *p*-value $p \geq 0.01$. Inability to reject this hypothesis would imply that manifestations of HPs are not observed in the CMB or that they are expected by ΛCDM . On the contrary, rejecting this hypothesis (p < 0.01) could give an indication towards the existence of HPs. Results of this analysis are reported in Section 5.3.

We calculated the statistics for both cases with two different methods, with the aim of comparing their performance.

(i) *Kolmogorov–Smirnov (KS test):* is a non-parametric test of equality of probability distributions. We employ the two-sample version of the test which relies on the *empirical cumulative distribution functions* (eCDFs) (Dekking et al. 2005). Assuming that two independent samples X_1, \ldots, X_m and Y_1, \ldots, Y_n are drawn with eCDF's $F_m(t)$ and $G_n(t)$, the KS test finds the maximum distance between both sampled probability distributions. As explained in Pratt & Gibbons (2012), the test statistics are given by

$$D_{mn} = \max |G_n(t) - F_m(t)| \tag{5}$$

$$D_{mn}^{+} = \max(G_n(t) - F_m(t))$$
(6)

$$D_{mn}^{-} = \max(F_m(t) - G_n(t))$$
(7)

Equation (5) is called the two-sided statistic, since it measures if G = F. Equations (6) and (7) are called one-sided statistics, since they test if $G \ge F$ and $G \le F$, respectively. Some advantages of KS test are that it does not depend on the underlying cumulative distribution function being tested and it is an exact test, with several desirable properties as consistency, and good power in detecting a shift in the median of the distribution (Walpole & Myers 2016), Janssen (2000). In our particular framework, it is important to note that when testing cases I and II the statistics used is defined according to equations (5) and (6), respectively.

When performing the KS-test for a fixed annulus size $\{r_{in}, r_{out}\}$, we computed the similarity between a single real map $\mathcal{M}_{r_{in},r_{out}}^{real}$ against $N = 10^3$ simulated maps $\mathcal{M}_{r_{in},r_{out}}^{im}$, and we obtained a set of *p*-values. We define the set of *p*-values as,

$$P_{i}(r_{in}, r_{out}) = \{ p(x, i) \mid x \in \mathscr{M}_{r_{in}, r_{out}}^{sim} \} \text{ for } i \in \{1, 4\},$$
(8)

where *i* refers to the four real sky maps presented in Section 3. From a single set $P_i(r_{in}, r_{out})$ we calculated the confidence interval (CI) $\mu(P_i(r_{in}, r_{out})) \pm \varepsilon(P_i(r_{in}, r_{out}))$ at a confidence level of 99.99 per cent. If for a given size $\{r_{in}, r_{out}\}$ we were to find $\mu(P_i(r_{in}, r_{out})) < 0.01$ this could give an indication of the existence of HPs. The other method that has been commonly used in the search of HPs in the real CMB sky map (An et al. 2020; Jow & Scott 2020) is based on proportion of simulated sky maps generating data as 'exceptional' as the real sky map:

(ii) *A-functions:* in Meissner (2012), the author claimed that the main disadvantage of KS is that it tends to be more sensitive to the bulk of the distribution than to the tails, and the A-functions were proposed to overcome this problem. These functions are defined as follows:

$$A^{+}(r_{\rm in}, r_{\rm out}) = -\frac{j}{N} \sum_{i=1}^{N} log(1 - F_{\hat{a}}(r_{\rm in}, r_{\rm out})^{j}), \tag{9}$$

$$A^{-}(r_{\rm in}, r_{\rm out}) = -\frac{j}{N} \sum_{i=1}^{N} log(1 - [1 - F_{\hat{a}}(r_{\rm in}, r_{\rm out})]^{j}),$$
(10)

where $F_{\hat{a}}(r_{\text{in}}, r_{\text{out}})$ is the cumulative distribution function of the normalized slope \hat{a} for all centers *c*, and *j* is a positive real number that

²Instead of using the built in function *healpy.rotator.angdist()* to compute the angular distance $d(\mathcal{P})$, we implement our own function with *Numba* package, which is twice as fast.

represents the relative weight of tails of the distribution. Distributions with an excess of extreme positive or negative values should give a large $A^+(r_{in}, r_{out})$ or $A^-(r_{in}, r_{out})$, respectively.

To compare the performance of the A-functions with the KS test, we followed they same approach as in An et al. (2020) and Jow & Scott (2020). The methodology is as follows: the A functions are computed setting $j = 10^4$ for each $\mathscr{M}_{rin,rout}^{im}$ and $\mathscr{M}_{rin,rout}^{eal}$, returning $\{A_{sim}^+(r_{in}, r_{out}), A_{sim}^-(r_{in}, r_{out})\}$ and $\{A_{real}^+(r_{in}, r_{out}), A_{real}^-(r_{in}, r_{out})\}$.

(i) Whenever $A_{sim}^-(r_{in}, r_{out}) > A_{real}^-(r_{in}, r_{out})$, the counter $N^-(r_{in}, r_{out})$, representing the number of simulated maps with an excess of extreme negative values, is increased by 1.

(ii) When $A_{sim}^+(r_{in}, r_{out}) > A_{real}^+(r_{in}, r_{out})$, the counter $N^+(r_{in}, r_{out})$ for simulated extreme positive values is increased.

Distributions with an excess of extreme values should give a large $A^+(r_{\rm in}, r_{\rm out})$ and $A^-(r_{\rm in}, r_{\rm out})$. Therefore, if for a certain size we found a counter $N^+(r_{\rm in}, r_{\rm out}) \sim 0$, this would mean a large excess of positive measurements, which is not expected by CCC. If $N^-(r_{\rm in}, r_{out} \leq 0.035) \sim 0$, it reflects that $\mathcal{M}_{r_{\rm in}, r_{\rm out}}^{real}$ has the largest population of negative extreme measurements, which could imply the existence of HPs.

4.4 Statistical methods for the location of Hawking points

The A-functions and the KS both test the presence or absence of HPs, but not their locations. To locate HPs we propose another analysis, whose aim is to store the location information of each anomaly.

(i) Location of HP candidates (HPC) at α significance level Because we have simulated $N = 10^3$ CMB sky maps, for a given center c and a size $\{r_{in}, r_{out}\}$ we have a set of N simulated measurements $m(c, r_{in}, r_{out})$ (either normalized slopes or Pearson correlation coefficients), which we can define as:

$$M(c, r_{\rm in}, r_{\rm out}) = \{m_i(c, r_{\rm in}, r_{\rm out}) \mid i \in \text{ simulated sky maps}\}$$
(11)

We sort this set by increasing value and we define a certain significance level α , that indicates the amount of extreme values that we expect in the tails. In the left tail of the simulated distribution $M(c, r_{\text{in}}, r_{\text{out}})$ we expect $\alpha \times N/2$ values. Thus, we take $t(c, r_{\text{in}}, r_{\text{out}}, \alpha)$, which is defined as the $\alpha \times N/2th$ value of our sorted set, to be the threshold for the detection of *HPs*.

When scanning the *ith* real CMB sky map for a certain location *c* and size $\{r_{in}, r_{out}\}$, if the measurement $m_i(c, r_{in}, r_{out})$ is smaller (more negative) then $t(c, r_{in}, r_{out}, \alpha)$ we consider this annulus $\mathcal{A}(c, r_{in}, r_{out})$ a HPC. Otherwise, it will not be considerate a candidate. Note that the annulus is a function of $\{r_{in}, r_{out}\}$, so we are able to locate it in the sky map. Finally, we compute the rate of HPC, defined as the number of HPC over the total number of locations *c* explored in percentage. We expect to find a HPC rate of $\alpha/2$ due to statistical fluctuations, but larger rates would imply the existence of HPs.

A similar procedure can be employed to measure the population in the upper tail, just by ordering $M(c, r_{in}, r_{out})$ by decreasing value. It is important to note that this procedure does not only point at HPC if they are anomalies in the data, but also locates them in the real CMB sky map.

4.5 Statistical methods for the reliability of the methodology

As a further proof of the performance of our methodology, we want to test whether we are able to capture ring-like structures with an artificial data set by employing the same methodology introduced in Section 4.4. To address this, we generated 1000 simulated CMB sky maps and we re-scaled them³ in range [-1, 1]. Afterwards, we inject 110 artificial annuli (*AA*) per sky map. Because we are unaware of how visible HPs are, we created five different types of AA with different amplitudes to assess performance. The amplitude of each type of AA is inversely proportional to its width σ and its radius *r* has a finite size $\in [r_{in}, r_{out}]$, as it has been illustrated in Fig. 1 (top). After injecting AA, the upper-bound of the temperature field increases due to the excess that we have introduced, as it is reflected in the colourbar of Fig. 1 (bottom).

Note that re-scaling the sky maps individually would not affect the detection of AA, since our algorithm searches for strong linear correlations in the input data. Moreover, one must note that HP are Gaussian-like structures, so not strictly Gaussian. However, to construct a mock data set we approximated their slope to a Gaussian function.

In Fig. 1 (top) we plot in solid line the portions of the Gaussians employed as a function of the number of pixels, to create different types of AA. These portions are employed to generate Gaussian radial profiles, which are projected in the 2D simulated sky maps and injected at random sky positions. As an example, in Fig. 1 (bottom) we represent in galactic Cartesian coordinates (l, b) different AA of a fixed size labeled according to the portion employed (measured in degrees; see top panel for details). Note that the size of AA is sampled at random from the uniform distribution of sizes defined in Section 4.2, with a limit $r_{out} \leq 0.07$ rad. Furthermore, the upper-bound of the temperature field is ≥ 1.0 because of the contribution of AA.

A single simulation is cloned five times to insert a single type of AA per sky map. We stored their locations and scanned the maps, obtaining a population of measurements of normalized slope \hat{a} and Pearson coefficient *r*. After that, we built a confidence interval of the population at a certain α significance level to select the most negative measurements. Because each extremely negative measurement has a certain location *c* and size { r_{in} , r_{out} }, we can count how many of these corresponding annuli intersect a single AA. If a single extremely negative annulus intersects an AA, then the AA is detected and labeled as such. Otherwise, we classify it as a *fake AA*.

We measured performance of our method in terms of the confusion matrix (Ting 2011). It is important to note that the amount of false positive is determined by the significance level α . Since we are only interested in correctly classifying true AA (i.e. in true positive), we measured performance in terms of True Positive Rate (TPR), False Negative Rate (FNR), Positive Predictive Value (PPV), and False Discovery Rate (FDR) (see Ting (2011) for details). In particular, for each CMB sky map we only compute TPR and PPV, because FNR and FDR can be derived from them, respectively.

5 RESULTS

In Section 5.1 we show the performance of our method when we employ a synthetic data set. In Section 5.2 we present the results of testing the reliability of the simulations, whereas in Section 5.3 we test the absence of HPs in the CMB sky map. For these last two sections, we employ the real sky maps SEVEM, SMICA, and Commander-Ruler, covered with their pre-defined masks, and CMB at 70 GHz sky map, masked by the Galactic belt mask, as well as 10³ simulated CMB maps. Note that when comparing the simulations against a certain real map, all-sky maps are covered with the same mask.

³We employ the rescaling function preprocessing.MinMaxScaler() from scikit learn (Pedregosa et al. 2011). Note that the rescaling function is applied to each individual sky map before injecting the AA.



Figure 1. (Top) Gaussian distributions employed to construct AA. The solid line represents the portion of the Gaussian that has been rotated in the vertical axis to form a surface of revolution. Afterwards, this three-dimensional surface was projected in a 2D simulated sky map. (Bottom) Example of AA projected in galactic Cartesian coordinates (*l*, *b*) measured in degrees that represent the angular distance. Each AA is of size { $r_{in} = 0.0075$, $r_{out} = 0.0225$ } and it is labeled according to the width of its generative portions in the top panel.

5.1 On the generation and detection of artificial Hawking points

As explained in Section 4.5, we simulated 10^3 artificial maps. Once we generated the maps, we scanned them with our procedure and we computed for each map the normalized slope and Pearson correlation coefficient (see Section 4.5). In Figs 2 and 3 we plot the mean TPR and the mean PPV as functions of the significance level α for the different widths σ (see Fig. 1 top panel).



Figure 2. Average TPR as a function of the significance level α for different Gaussian rings. The solid lines represent the results of Pearson coefficient *r* and the dotted lines are the results of the normalized slope \hat{a} .



Figure 3. Average PPV as a function of the significance level α for different Gaussian rings. The solid lines represent the results of Pearson coefficient *r* and the dotted lines are the results of the normalized slope \hat{a} .

From Fig. 2 can observe that as we increase σ , the TPR and the PPV decrease. We speculate that for large σ , the TPR of the normalized slope \hat{a} would be slightly better than the one of the Pearson coefficient r, because the Pearson coefficient points out the strongest correlations in the data. Note that, FNR has a complementary behaviour to TPR. In Fig. 3, we conclude that the Pearson coefficient r is less precise than the normalized slope \hat{a} , with a ~20 per cent difference for all α . Nevertheless, with both measurements, we can detect most of the rings (around 95 per cent TPR).

5.2 On the reliability of the simulated cosmic microwave background maps

To test the quality of the simulations we compared $10^3 \mathcal{M}_{r_{in},r_{out}}^{sim}$ against $\mathcal{M}_{r_{in},r_{out}}^{teal}$ of a selected real sky map in the region where $r_{out} \ge 0.035$, i.e. where HP are not expected to be present according to CCC. For this aim, we use the approach introduced in Section 4.3 with a significance level $\alpha = 0.01$. After performing the test we obtain a distribution of $10^3 p$ -values, and we compute its confidence interval (CI) at 99.99 per cent confidence level. To have a reference mean p-value, we repeated the same procedure on simulated maps only, by comparing a simulated sky map against 10^3 simulations. Assuming that the simulations of CMB are very similar to the real sky maps, it would be expected that for this test we would obtain $\mu(P_i) \ge 0.01$



Figure 4. Mean *p*-values at four standard deviations as a function of the outer radius where HP is not expected theoretically. For this computation 10^3 simulated sky maps were compared against a single simulated sky map according to Λ *CDM* (dashed lines) and a real sky map (solid lines). All sky maps were masked according to the pre-defined mask obtained for their analysis, except CMB at 70 GHz which was masked with the Galactic belt mask, as reflected in parenthesis in the legend.

for a given *ith* sky map, meaning that the simulated maps are not significantly different from real CMB sky maps.

In Fig. 4 we represent the CI of the resulting p-values as a function of the outer radius of the annuli explored for the comparisons of real-simulated (solid lines) and simulated-simulated (dashed lines) sky maps. Note that each pair of real-simulated and simulatedsimulated sky maps have been masked with the same pre-defined mask. From the results reported in Fig. 4, it can be noticed that in general, we cannot reject the hypothesis that the pairs real-simulated and simulated-simulated come from the same distribution, except for SEVEM sky maps. Another exception, but marginal, is the real CMB at 70GHZ sky map, where for the size $\{r_{in}, r_{out}\} = \{0.057, 0.060\}$ in particular (far most right panel of Fig. 4), we obtain a p-value 0.1674 ± 0.0070 , whose lower bound is lower than the pre-defined threshold. One may think that this may be due to the low number of pixels in the annuli. However, in this region, we explored large annuli of ~13 000 pixels. It is relevant to note that Commander-Ruler might seem to have similar behaviour as CMB at 70 GHZ at the same size, but its lower bound does not intersect $\alpha = 0.01$.

The results of SEVEM seem to indicate that there is a strong influence of the mask employed. It would be interesting to further investigate the influence of this mask in the context of anomalous searches in the CMB sky map.

5.3 On the absence of Hawking points in the cosmic microwave background

To test the absence of HPs in the CMB, we compared again 10^3 samples $\mathcal{M}_{r_{in},r_{out}}^{sim}$ against $\mathcal{M}_{r_{in},r_{out}}^{eal}$ of a selected real sky map with KS test, where we used the approach II explained in Section 4.3 with a significance level $\alpha = 0.01$.

Overall, we did not find any $\mu(P_i) < 0.01$, which suggests that HP are not present in the CMB. However, a possible explanation for this result might be that there is not enough HP to produce a significant shift with respect to the reference distribution.

For completeness, we calculated the counters $N_{r_{in},r_{out}}^{-}$ and $N_{r_{in},r_{out}}^{+}$ for the normalized slope \hat{a} , with the A functions setting $j = 10^4$. As we discussed before, this methodology was proposed to give more

importance to the tails of the distribution, because KS test gives more weight to the bulk instead (see Section 4.3). When computing $N_{r_{\rm in},r_{\rm out}}^{-}$ and $N_{r_{\rm in},r_{\rm out}}^{+}$ we did not find statistically significant results for $\alpha = 1$ per cent, i.e. we did not find an annulus size $\{r_{\rm in}, r_{\rm out}\}$ for which at most 10 simulated sky-maps outperformed the real skymaps. Thus, we were unable to reproduce the results from An et al. (2020), in which the authors reported to have identified HPs at a 99.98 per cent confidence level.

5.4 On the location of Hawking points in the cosmic microwave background

Finally, we built a confidence interval to obtain the most negative measurements, as we described in Section 4.4, following the assumption that the simulations represent the real CMB sky maps. In An et al. (2020) and Penrose (2010) it is stated that HPs should have extremely negative measurements,⁴ although no theoretical threshold is available for this value. Therefore, we computed different confidence intervals for $\alpha = [1 \text{ per cent}, 5 \text{ per cent}]$ for CMB at 70 GHz, SMICA and Commander-Ruler sky maps, since they are similar to the simulations (see Section 5.2 for details).

Without considering these results as proof for HPs, we report on the largest rates of HPC found at $\alpha = 1$ per cent for these sky maps. For the normalized slope \hat{a} one expects a HPC rate of 0.5 per cent. The maximum rates obtained were of 0.734 per cent for ($r_{in} = 0.018$, $r_{out} = 0.023$) in CMB at 70GHz, 0.781 per cent for ($r_{in} = 0.003$, $r_{out} = 0.007$) in SMICA, and 0.903 per cent for ($r_{in} = 0.018$, $r_{out} = 0.028$) in Commander-Ruler. We do not consider these deviations as exceptional and believe that reporting on the significance of these deviations would be over-interpreting the data.

Fig. 5 shows in black the most negative annuli indicated by the authors in An et al. (2020), and in dark blue, dark green, and dark red 25 of the most extreme HPC found by our methodology at $\alpha = 1$ per cent for CMB at 70 GHz, SMICA, and Commander-

⁴We also explored the extremely positive measurements for completeness but no interesting results were found.



Figure 5. HPC obtained with normalized slope \hat{a} measurement at 1 per cent significance level, represented in orthographic projection: in black we plotted the most negative annuli presented in (An et al. 2020), whereas in dark blue, dark green, and dark red the HPC found by our confidence interval in CMB at 70 GHZ, SMICA, and Commander-Ruler, respectively. The background CMB sky map corresponds to SMICA sky map, for illustration.

Ruler, respectively. As it can be observed, the annuli of An et al. (2020) and ours do not coincide, due to the different methodologies employed. Notoriously, some locations of An et al. (2020), CMB at 70 GHz and Commander-Ruler partially overlap and others are in a close neighbourhood, despite employing different masks. It would be interesting to study these locations in detail in the future, as well as the influence of the masks used for this type of analysis.

6 CONCLUSION

The main goal of this work was to search for ring-like anomalies in the CMB. Because we are searching for linear relationships between the measured temperature *T* and the angular distance *d* in an annulus, we measured the normalized slopes \hat{a} and Pearson coefficients *r* for different { r_{in} , r_{out} } sizes. The measurements were performed on real and simulated CMB sky maps with different masks. We compared both distributions of measurements to draw conclusions about the reliability of the simulations and the absence of HPs in the CMB. Furthermore, to measure the performance of our method with a mock data set, we constructed an artificial data set of ring-like structures and we detected artificial annuli with a *TPR* ~ 95 per cent.

In this study, when measuring the quality of the simulations employed, we observed a mismatch between the real CMB maps and the simulations, in the region where ring-like structures associated with HPs are not expected when we employed the SEVEM sky map. This behaviour was not observed when we used CMB with Galactic belt mask, SMICA or Commander-ruler's masks.

We also postulated the absence of the ring-like manifestations of HPs in the CMB, and we were unable to statistically reject this hypothesis by employing the Kolmogorov–Smirnov test, and thus we could not reproduce the results of An et al. (2020). We think that these negative results may be because, if HPs exist, they may be rare in the real CMB map.

To treat HPs as anomalies in the CMB, from simulated sky maps we generated CI for the normalized slope and Pearson correlation coefficient at different significance levels α . When setting the confidence interval at α per cent significance level we were expecting (in absence of HPs) HPC rates of at most $\alpha/2$ due to the randomness of the data. We searched therefore for HPC rates larger than this value and found them for the normalized slope \hat{a} at $\alpha = 1$ per cent significance level in the CMB at 70 *GHz*, SMICA and Commander-Ruler sky map, which implies that there are more negative measurements in the real CMB sky maps than in the simulations. Moreover, we located the most extreme values as can be observed in Fig. 5.

Finally, we foresee a possibility, albeit speculative, to apply the methodology presented in this article to search for imprints of HPs in the Cosmological Gravitational-wave Background (CGB) of unresolved binary black-hole inspirals. The HP's imprint on the energy distribution of the very early universe should have had a similar influence on the distribution of primordial black holes as it did on the formation of ring-like distributions in the CMB. The details of the formation and merger rates of primordial BBH is subject of ongoing theoretical investigation. However, it will be interesting to see whether such rings found in the CMB are not statistical artefacts, and would serve as an independent indication for the existence of HPs. The theoretical and observational feasibility of this suggestion should be further investigated.

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DATA AVAILABILITY

The data underlying this article are available in Planck Legacy Archive (PL) (Dupac et al. 2015), at https: //www.cosmos.esa.int/web/planck/pla. The data sets were obtained from observations with Planck (http://www.esa.int/Planck), an ESA science mission with instruments and contributions directly funded by ESA Member States, NASA, and Canada.

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