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Stellar-mass microlensing of gravitational waves

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ABSTRACT

When gravitational waves (GWs) pass through the nuclear star clusters of galactic lenses, they may be microlensed by the stars. Such microlensing can cause potentially observable beating patterns on the waveform due to waveform superposition and magnify the signal. On the one hand, the beating patterns and magnification could lead to the first detection of a microlensed GW. On the other hand, microlensing introduces a systematic error in strong lensing use-cases, such as localization and cosmography studies. By numerically solving the lensing diffraction integral, we show that diffraction effects are important when we consider GWs in the LIGO frequency band lensed by objects with masses $\lesssim 100 \, M_{\odot}$. We also show that the galaxy hosting the microlenses changes the lensing configuration qualitatively, so we cannot treat the microlenses as isolated point mass lenses when strong lensing is involved. We find that for stellar lenses with masses $\sim 1 \, M_{\odot}$, diffraction effects significantly suppress the microlensing magnification. Thus, our results suggest that GWs lensed by typical galaxy or galaxy cluster lenses may offer a relatively clean environment to study the lens system, free of contamination by stellar lenses, which can be advantageous for localization and cosmography studies.

Key words: gravitational lensing: micro-gravitational lensing: strong-gravitational waves.

1 INTRODUCTION

Both gravitational waves (GWs) and electromagnetic (EM) waves can be gravitationally lensed when propagating near massive astrophysical objects, such as galaxies and galaxy clusters (Ohanian 1974; Thorne 1982; Deguchi & Watson 1986; Wang, Stebbins & Turner 1996; Nakamura 1998; Takahashi & Nakamura 2003). To date, only the lensing of EM waves has definitively been observed, but several searches for GW lensing have already been performed (Hannuksela et al. 2019; Li et al. 2019a; Dai et al. 2020; Liu, Hernandez & Creighton 2020; McIsaac et al. 2020; Pang et al. 2020).

Suppose the GW is lensed by a galaxy or a galaxy cluster only. In that case, we can use the geometrical optics approximation to solve for the trajectory, the arrival time of distinct GW images, and their image types (Takahashi & Nakamura 2003). These GW images will only differ in their amplitudes, arrival times, and overall phases.¹ Thus, we can identify the strongly lensed images as repeated events with identical frequency evolution using matched filtering and Bayesian analysis (Haris et al. 2018; Hannuksela et al. 2019; Li et al. 2019a; Dai et al. 2020; Liu et al. 2020; McIsaac et al. 2020).

If we localized such strongly lensed GWs, we might be able to perform precision cosmography studies at high redshift (Sereno et al. 2011; Liao et al. 2017; Cao et al. 2019; Li, Fan & Gou 2019b; Hannuksela et al. 2020), connect binary black holes to their host galaxy properties and investigate formation channels (Chen & Holz 2016; Hannuksela et al. 2020), and conduct improved tests of the GW polarization content (Goyal et al. 2020).² Other intriguing usecases in, e.g. cosmography, have been documented in (Oguri 2019). However, most of these science cases, as well as the localization studies, rely on a clean environment devoid of systematic errors introduced due to microlensing by stars.³

In particular, when GWs are strongly lensed by galaxy and galaxy clusters, their trajectories might pass through dense nuclear star clusters, introducing a non-negligible chance of microlensing (Christian, Vitale & Loeb 2018). The stellar lens would then introduce additional microlensing effects. In GW lensing localization studies, they can introduce a sizable error in the magnification ratio when the geometrical optics limit is assumed (Hannuksela et al. 2020). In general, microlensing could lead to systematic errors that will be counter-beneficial to studies of lensed transient events (see

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¹This generally applies to (2,2) modes. However, if the GWs exhibit higher order modes or precession, the so-called saddle point images (type-II) could experience non-trivial waveform changes (Dai & Venumadhav 2017; Ezquiaga et al. 2020).

 $^{^{2}}$ We note that these latter polarization tests could be done even for nonlocalized events (Goyal et al. 2020). Still, the localization would significantly improve the tests, as we could solve the sky location and the image properties independently in the EM band (Hannuksela et al. 2020).

 $^{{}^{3}}$ For example, a substantial fraction of the error budget in the localization studies proposed in Ref. Hannuksela et al. (2020) is dominated by microlensing.

discussion in Oguri 2019) and indeed almost any study relying on GW localization (e.g. Sereno et al. 2011; Baker & Trodden 2017; Collett & Bacon 2017; Fan et al. 2017; Liao et al. 2017; Cao et al. 2019; Li et al. 2019b; Hannuksela et al. 2020).

Luckily, as GWs have much longer wavelengths than typical EM waves, diffraction effects can suppress microlensing when the stellar lens has an Einstein radius comparable to the wavelength of the GWs (Oguri 2019). However, microlenses in the wave optics limit have been mostly studied in isolation (see, however, Diego et al. 2019, Meena & Bagla 2020, and Diego 2020) for an interesting exploration of microlensing effects on top of a macromodel of constant external convergence and shear in the extreme high-magnification regime).

We consider the typical case of a stellar lens on top of a galactic lens model at moderate magnification, similar to the usual strong lensing system we expect to observe. We focus on the waveform suppression effects brought forth by wave optics diffraction and elaborate on its implications. Much of our work is motivated by the discussion in Ref. Oguri (2019), which discusses some of these wave optics suppression effects; our work aims to quantify the wave optics suppression when macromodels are involved and investigate their dependence on the microlens properties and position in order to obtain a qualitative understanding.

We first lay out the procedures for treating a compound lens system consisting of lenses with masses and length-scales orders of magnitudes apart. Then, we show that the geometrical optics approximation is not sufficient to treat the case of stellar-mass microlensing for LIGO/Virgo. After that, we quantify the deviations introduced by microlenses to the GW waveforms and show that they would generally not affect events at LIGO/Virgo frequencies. Finally, we will put our results in an astrophysical context and elaborate on the implications and potential use-cases, especially those related to the localization of GW sources and cosmography.

2 METHODS

Strongly lensed GWs may be detectable at design sensitivity, based on current lens and binary models (Li et al. 2018; Ng et al. 2018; Oguri 2018). The typical analysis considers gravitational lensing by a macromodel, such as a galaxy. However, microlensing by, e.g. a point mass within a larger galaxy macromodel may significantly affect the lensed GW waveform (Christian et al. 2018; Lai et al. 2018; Diego et al. 2019; Jung & Shin 2019; Diego 2020).

Suppose the wavelength of the GW λ is comparable to the Einstein radius of the point mass θ_m . In that case, there will be significant diffraction effects as the 'obstacle' has a size smaller than the wavelength, in which case the propagation of the wave will be less disturbed and the geometrical optics approximation no longer holds (Oguri 2019). Following Takahashi & Nakamura (2003), this can be shown by considering a double slit experiment set-up with the slit width comparable to $\theta_m \sim \sqrt{mD}$, where *m* is the lens mass and *D* is the distance from the slit to the screen (analogous to the distance from the lens to the observer D_L). Then, the maximum magnification of the wave flux at the central peak is of the order $\sim \theta_m^2/(D\lambda) \sim m/\lambda$. When $\lambda \gg m$, the lens is of a negligible size, and the magnification is suppressed.

In this section, we review the necessary methods to treat lensing in the full wave-optics regime. Note: in this paper, we work in units where c = G = 1.

2.1 Computing the diffraction integral

Fig. 1 shows the geometry of a typical lensing configuration. A GW source is positioned at an angular diameter distance of D_L . In contrast,



Figure 1. Schematic diagram of the lensing geometry. We use the thin-lens approximation and assume that all of the lens mass resides on the lens plane. This diagram is not drawn to scale; the lengths D_{LS} , D_{L} , and D_{S} are very large compared to $\|\vec{\eta}\|$ and $\|\vec{\xi}\|$.

a massive object, or 'lens', is positioned near the straight-line path between the source and the observer at an angular diameter distance D_S . As D_L and D_S are very large compared to the length-scale of the lens, we can apply the thin-lens approximation, where the lensing of GWs occurs in the plane of the lens.

When GWs are radiated from the source, the portion that passes near the lens might be focused towards the observer. As the lens's length-scale is small compared to the distances between the source, lens, and observer, we can approximate the paths of lensed 'rays' of GWs as straight line segments that change their direction abruptly at the lens plane. In Fig. 1, we show one of these rays. If we draw all possible rays from the source that would arrive at the observer, we would observe a one-to-one correspondence of such rays with points on the lens plane. Moreover, as these rays take different space–time paths, they would arrive at the observer at different times. Thus, we can construct a function t_d that maps a point on the lens plane $\vec{\xi}$ to the arrival time of the ray that passes through that point, given a source position $\vec{\eta}$. For analytical calculations with $\vec{\xi}$ and $\vec{\eta}$, it is easier to work in units normalized by the Einstein radius:

$$\theta_{\rm E} = \sqrt{\frac{4M_{\rm L}D_{\rm L}D_{\rm LS}}{D_{\rm S}}},\tag{1}$$

where $M_{\rm L}$ is the total mass of the lens and $D_{\rm LS}$ is the angular diameter distance between the lens and the source (in systems with multiple lenses, we will revert to un-normalized units to avoid confusion). In these normalized units, writing $\vec{x} = \vec{\xi}/\theta_{\rm E}$ and $\vec{y} = \vec{\eta}/\theta_{\rm E}$, the time delay function $t_{\rm d}$ is given by

$$t_{\rm d}(\vec{x}, \, \vec{y}) = \frac{D_{\rm S} \theta_{\rm E}^2 (1 + z_{\rm L})}{D_{\rm L} D_{\rm LS}} T(\vec{x}, \, \vec{y}),\tag{2}$$

with

$$T(\vec{x}, \vec{y}) = \frac{1}{2} \|\vec{x} - \vec{y}\|^2 - \phi(\vec{x}) - T_0(\vec{y}),$$
(3)

where $T_0(\vec{y})$ corresponds to the arrival time of the first image, and $\phi(\vec{x})$ is the Fermat potential that depends on the nature of the lens (e.g. we have $\phi(\vec{x}) = \ln ||\vec{x}||$ for a point mass lens). Besides, we consider the time delay on cosmological distances, such that equation (2) includes a factor of $1 + z_L$, where z_L is the lens's redshift.

Let the GW waveform observed without the presence of the lens be h(f) in the frequency domain. If the waveform observed with lensing

is $h_{\rm L}(f)$, we can quantify the change in the waveform due to lensing effects by the amplification factor

$$F(f) = \frac{h_{\rm L}(f)}{h(f)},\tag{4}$$

which is complex in general. If ϕ and hence t_d is known, we can obtain F(f) by the diffraction integral (Schneider, Ehlers & Falco 1992)

$$F(f) = \frac{D_{\rm S} \theta_{\rm E}^2 (1+z_{\rm L})}{D_{\rm L} D_{\rm LS}} \frac{f}{i} \iint_{\mathbb{R}^2} {\rm d}^2 \vec{x} \; {\rm e}^{2\pi i f t_{\rm d}(\vec{x},\vec{y})}.$$
(5)

By using a dimensionless frequency scale $w = 8\pi M_L(1 + z_L)f$, we arrive at

$$\tilde{F}(w) = -iw \iint_{\mathbb{R}^2} \mathrm{d}^2 \vec{x} \ \mathrm{e}^{iwT(\vec{x},\vec{y})}.$$
(6)

The integrand in equation (6) is highly oscillatory for high w, so the integral is computationally expensive to solve with typical numerical integration techniques even for simple lens models. To solve this integral, we follow a similar method mentioned in Ulmer & Goodman (1994) and used in Diego et al. (2019), where we compute an area integration directly in the lens plane and take its Fourier transform, which is easier to implement for general lens models and gives F(f) for a wide frequency spectrum with a single calculation. The case of microlensing on a macromodel introduces important subtleties to this method, making the evaluation of the integral not as straight forward as models containing lenses with masses all of the same order. In particular, the regions around the time delay function's saddle points require careful treatment (see Section 4.2). These cases and the detailed methodology for calculating equation (6) for general lens models will be discussed in a later work. In this paper, we focus on the results from the minimum time delay image of the macro model, which can already give us insights into the effects of stellar lensing on GWs.

2.2 Geometrical optics approximation

For $w \gg 1$, we can work in the geometrical optics limit, where the integral in equation (6) will mostly be contributed by the stationary points of $T(\vec{x}, \vec{y})$ (Fermat's principle). We call these stationary points the image positions of the lensing configuration. In such a limit, $\tilde{F}(w)$ is given by (Schneider et al. 1992)

$$\tilde{F}(w) = \sum_{j} |\mu(\vec{x_j})|^{1/2} \exp\left(i\pi(2wT(\vec{x_j}, \vec{y}) - n_j)\right),\tag{7}$$

where $\vec{x_j}$ are the image positions, $\mu(\vec{x}) = \det(\partial \vec{y}/\partial \vec{x})$ is the image magnification, $n_j = 0, \frac{1}{2}, 1$ when $\vec{x_j}$ is at a minimum, saddle, and maximum point of $T(\vec{x}, \vec{y})$, respectively. We solve the image properties in the geometrical optics limit using the LENSINGGW package (Pagano, Hannuksela & Li 2020), powered by LENSTRON-OMY (Birrer & Amara 2018).

2.3 Microlensing

Strong lensing occurs when a GW passes by a lens with an impact parameter \leq the Einstein radius. A scenario particularly interesting would be when a GW passes inside the Einstein ring of two lenses of drastically different lens scales. It is useful for such cases to introduce the notion of 'macro' and 'micro' lens models. We refer to the lensing images produced by the two models as macroimages and microimages, respectively, following Diego et al. (2019).



Figure 2. Schematic diagram of an example scenario of microlensing on a macromodel. (Top) In the geometrical optics limit, one can treat the waves as rays propagating from the source to the observer, only taking specific routes through particular points on the lens plane. If there were no microlens, there would be two of these rays, passing through macroimage points (the blue points) on the lens plane (bottom panel) before arriving at the observer. However, when a microlens (a small black dot on the lens plane) is present near a macroimage, the beam (shown in the dotted lines) might be split into multiple ones and pass through different points on the lens plane, which correspond to microimage positions (the red points). The distance between the microlens and the macroimage is written as η_m and called the micro impact parameter.

Let there be some lenses of mass $\sim M$ and some of mass $\sim m$ in the lens plane (where the thin-lens approximation is invoked), and let $M \gg m$. For simplicity, let there be no relevant lenses in the intermediate-mass range. We can then define the $\sim M$ lenses to be the macrolenses, and those $\sim m$ to be the microlenses. We can obtain an intuitive understanding of the behaviour of GWs lensed by such a system by thinking of how the lenses would split the GW beams. We can think of the macrolenses splitting the beams into separate rays (macroimages), and then the microlenses split the beams further (into microimages). An example is shown in Fig. 2.

However, there is a caveat: when thinking of lensed GWs as propagating towards us by taking certain discrete ray-like paths, we have implicitly invoked the geometrical optics approximation. As mentioned previously in this section, if the wavelength of the GWs is comparable to the Einstein radius of the lenses, diffraction effects will occur, and the GWs will no longer take only a discrete



Figure 3. The lens plane of an SIS macromodel of mass $M = 10^{10} \text{ M}_{\odot}$ with a microlens of mass $m = 30 \text{ M}_{\odot}$ near the minimum macroimage. The source position measured from the centre of the SIS lens and projected on to the lens plane (macro impact parameter) is $\eta_{\text{SIS}} = 0.1 \theta_{\text{SIS}}$, while the microlens is placed $\eta_{\text{m}} = 1.0 \theta_{\text{m}}$ away from the macroimage. The contour lines of the time delay function t_{d} are shown in grey. (Left-hand panel) view of the complete model, including the source position and macroimages. The macroimage on the left is of type-II (negative parity) as it is a saddle point of t_{d} , while that on the right is of type-I (positive parity). (Centre panel) zoom in on the region around the type-I minimum macroimage. The microlens splits the macroimage into four microimages, two of type-I (both minimum points) and two of type-II. (Right-hand panel) Further zoom-in on to the macroimage position. Note that as the macroimage is split into microimages, the point corresponding to the macroimage position is not a stationary point of t_{d} anymore; it is an actual image only when the microlens is absent.

number of paths. The next section will show that the geometrical optics approximation is insufficient for treating microlenses of stellar mass for GWs detectable by LIGO. None the less, the microimage positions and the macroimage positions are always the stationary points of the time delay function t_d , and it is convenient to keep track of their positions even if we are working with a full wave-optics treatment.

The Einstein radii of the microlenses are orders of magnitudes smaller than those of the macrolenses. The difference in arrival time between a group of microimages near a particular macroimage is also orders of magnitude below the difference in arrival time between macroimages. Therefore, we can carry out our integration in equation (6) for the microimages near the minimum macroimage of the macromodel (galactic lens), that is, within a small domain on the lens plane near the macroimage. We will then obtain an amplification factor F(f) that corresponds to the interferences between the relevant microimages with diffraction included. For saddle point macroimages, we will have to cover a much more extensive integration domain. This is to be performed in a later work (see also Section 4.2).

3 RESULTS

This section quantifies the effects of stellar microlenses on GWs (within the LIGO frequency band) lensed by a galaxy. We place the source at a redshift of $z_{\rm S} = 1$ and place a galactic lens at $z_{\rm L} = 0.5$. For our galactic macromodel, we use a singular isothermal sphere (SIS) lens of mass $10^{10} \,\mathrm{M_{\odot}}$. We will only consider cases corresponding to strong lensing. The macro impact parameter *y* (position of the source in the sky with respect to the centre of the SIS macromodel) is less than θ_{SIS} , the Einstein radius of the SIS macromodel. For such cases, we will see two macroimages, one corresponding to a minimum point

in the time delay function, and the other corresponding to the saddle point. Then, we introduce point-mass microlenses in the vicinity of the minimum macroimage. We can naively treat the minimum macroimage position as the 'source position' for the microlensing configuration and define the micro impact parameter η_m as the distance of the microlens from the macroimage position.

We assume that the microlens is hosted by the macromodel galaxy, which will likely be true for most cases of microlensing where the microlens is a star from the nuclear cluster of the galaxy, so we can treat the macrolens and the microlens as residing on the same plane in the sky (Diego et al. 2019). If the microlenses are of stellar mass, say $m < 100 \text{ M}_{\odot}$, the arrival time of the microimages will reside within a time window that is less than the period of GWs measured by LIGO. Thus, we will have to use the methods discussed in the previous section to recover the amplification factor for the signal measured that corresponds to the lensed GW rays near the macroimage.

In this section, as we are working with two very different lengthscales corresponding to the macromodel and microlenses, we will revert to unnormalized units of length, i.e. using $\vec{\xi}$ and $\vec{\eta}$ instead of \vec{x} and \vec{y} . We denote the norms of the vectors $\xi = \|\vec{\xi}\|$ and $\eta = \|\vec{\eta}\|$, etc. Relevant lengths for the SIS macromodel are the macro impact parameter (distance from the centre of the SIS lens to the source, projected on to the lens plane) η_{SIS} , and the Einstein radius of the SIS lens θ_{SIS} . For microlenses near a parent macroimage, we denote the micro impact parameter (distance between the parent macroimage and the microlens on the lens plane) as η_{m} , and the Einstein radius of the microlens as θ_{m} .

3.1 The necessity of a full wave-optics analysis

Fig. 3 shows the configuration of the full lens model and the contours of the time delay function for the case of a macro impact parameter



Figure 4. The normalized norm (top, left axis) and phase (bottom, left axis) of the frequency domain amplification factor F(f) near the minimum macroimage for the lensing set-up described in Fig. 3 (30 M_{\odot} microlens). The deviation of the geometrical optics approximation (the red-dashed line) and the full wave optics treatment (the red solid line) demonstrates that wave optics effects are important for stellar lenses of lower masses, and they suppress the amplification factor. The disagreement between treating the microlens in isolation (the red-dotted line) and considering both the macro and microlenses (the red solid line) shows that we have to also consider the macromodel's contribution to the time delay function in our analysis. The PSD of LIGO is plotted in the grey-dotted lines with the axis on the right of each panel.

 $\eta_{\text{SIS}} = 0.1 \,\theta_{\text{SIS}}$, micro impact parameter $\eta_{\text{m}} = 1.0 \,\theta_{\text{m}}$, and microlens mass $m = 30 \,\text{M}_{\odot}$. The microlens is placed on the straight line between the SIS centre and the minimum macroimage position. The macroimage and microimage positions are found with the help of the LENSINGGW package (Pagano et al. 2020).

We can work in the geometrical optics limit for the macromodel (the SIS lens) due to the lens's considerable mass. We will observe two GW signals of the same phase but different amplitudes and arrival times (see the two macroimages in the left-hand panel of Fig. 3). In this case, the macroimage only induces an overall magnification on the waveform, such that F(f) is a constant.

However, the addition of a stellar-mass lens near the macroimage disturbs the time delay function near the arrival time of the macroimage, causing F(f) to deviate from the constant value. Fig. 4 shows F(f) for the GW rays that come from around the minimum macroimage. Note that the amplification factor is normalized by $\sqrt{\mu}$, where μ is the magnification of the macroimage in the geometrical optics limit. If we work with the geometrical optics approximation and use equation (7), we obtain the dashed curve, which deviates significantly from the results without approximations for lower frequencies, showing that a full wave-optics analysis is necessary when dealing with microlenses.



Figure 5. Same as Fig. 4, but with a point mass microlens of mass $m \in \{1, 5, 10, 30\}$ M_{\odot}, placed accordingly at a distance of $\eta_m = 1.0 \theta_m$ away from the macroimage position similar to the set-up in Fig. 3. $F/\sqrt{\mu}$ converges to the constant limit of 1 for low frequencies and low microlens masses. We show the geometrical optics approximation results for a 1 M_{\odot} microlens in the green-dashed lines. The wave optics diffraction effects suppress the waveform relative to the geometrical optics approximation.

We also demonstrate that if we naively treated the microlenses independently of the macromodel (in isolation), we obtain the dotted curve in Fig. 4 instead, corresponding to the standard analytical expression for the amplification factor of the point mass lens (see Peters 1974). This amplification factor is significantly different from the full non-approximate amplification factor. In fact, by observing that the microlens splits the macroimage into four microimages instead of two in the centre panel of Fig. 3, we can already infer that the macromodel would introduce qualitative differences from the case of an isolated point mass. This further confirms the results in Diego et al. (2019, 2020) and Pagano et al. (2020) that it is necessary to consider the macromodel when treating microlensing in the presence of strong lensing.

3.2 Waveform suppression due to diffraction

We saw that the normalized amplification factor in our full waveoptics analysis reduces to unity as $f \rightarrow 0$, which corresponds to the limit when the wavelength of the GW $\lambda > \theta_m$, where the waves would propagate through the microlens unimpeded as diffraction effects dominate. This effectively means that GWs will be largely unaffected by the microlenses in the very low-mass regime. We examine the level of waveform suppression for different microlens masses in Fig. 5. With $m \in \{1, 5, 10, 30\} M_{\odot}$, we see that lower microlens masses correspond to amplification factors approaching 1



Figure 6. The frequency domain (top) and time domain (bottom) waveforms for the cases $m \in \{0, 10\}M_{\odot}$ for the set-up shown in Fig. 3. The waveform obtained for $m = 10 M_{\odot}$ from the geometrical optics limit is plotted in dashed lines. $m = 0 M_{\odot}$ corresponds to the case where there is no microlens. The PSD of aLIGO is also plotted in the top panel in the black-dotted lines for reference.

at most relevant LIGO/Virgo frequencies, implying that the GW signal is amplified only by the macroimage magnification. We also plot the frequency domain and time domain waveforms for $m \in \{0, 10\} M_{\odot}$ in Fig. 6. Here, an IMRPhenomD waveform of a $30 + 30 M_{\odot}$ binary black hole merger generated by PYCBC (Nitz et al. 2020) is used. The result obtained from the geometrical optics approximation for the $m = 10 M_{\odot}$ waveform is also shown in dashed lines, showing that we would overestimate the deviations of the waveform due to microlensing if we work in the geometrical optics limit.

Then, we investigate how the microlens location relative to the macroimage affects waveform suppression. Fixing $m = 10 \,\mathrm{M}_{\odot}$, we vary the micro impact parameter $\eta_{\mathrm{m}} \in \{0.1, 0.3, 0.5, 0.7, 1.0\} \,\theta_{\mathrm{m}}$ and calculate the amplification factors at different image positions. As shown in Fig. 7, the amplification factor converges to the same curve at low frequencies, suggesting that the effects of waveform suppression are similar regardless of the microlens location. This behaviour is also observed in the case of isolated point mass lenses (Nakamura 1998; Takahashi & Nakamura 2003).

We then quantify the differences introduced by microlensing to the lensed waveforms. We first define

$$h_{\rm L,full}(f) = F(f)h(f),\tag{8}$$

$$h_{\rm L,macro}(f) = \sqrt{\mu} h(f). \tag{9}$$



Figure 7. Same as Fig. 5, but this time fixing the microlens mass at $m = 10 \,\mathrm{M}_{\odot}$ while varying the micro impact parameter $\eta_{\mathrm{m}} \in \{0.1, 0.3, 0.5, 0.7, 1.0\} \,\theta_{\mathrm{m}}$. Due to diffraction effects, the amplification factors in the lower frequency region are suppressed to the same limit regardless of the micro impact parameter.

Then, we define the effective micro-magnification by

$$\mu_{\rm m} = \frac{(h_{\rm L,full} \mid h_{\rm L,full})}{(h_{\rm L,macro} \mid h_{\rm L,macro})},\tag{10}$$

where

$$(a|b) = 4 \operatorname{Re} \int_{f_{\text{low}}}^{f_{\text{high}}} \frac{a(f)b^*(f)}{S_n(f)} \mathrm{d}f$$
(11)

is the inner product weighted by the power-spectral density (PSD) $S_n(f)$ of LIGO. By taking the noise-weighted inner product, we remove the frequency dependence, so we can now approximate the change induced by the microlens on the amplification of the GW waveform. In Fig. 8, we plot $\sqrt{\mu_m}$ for $m \in (1, 100) M_{\odot}$ and $\eta_m \in (0.1, 1.0) \theta_m$. For h(f), we again use an IMRPhenomD waveform of a $30 + 30 M_{\odot}$ binary black hole merger, generated with PYCBC (Nitz et al. 2020). We took the square root because the amplification to the waveform is $\sim \sqrt{\mu_m}$. If the microlens were absent, $h_{L,\text{full}} = h_{L,\text{macro}}$ and equation (10) reduces to $\mu_m = 1$. For lower m, μ_m does not significantly deviate from unity. For $m \leq 3 M_{\odot}$, $\sqrt{\mu_m}$ is larger than 1 by ≤ 5 per cent.

To further quantify the deviation in the waveforms, we define the waveform overlap, which is given by

$$\mathcal{O}[h_{\mathrm{L,macro}}, h_{\mathrm{L,full}}] = \frac{(h_{\mathrm{L,full}} \mid h_{\mathrm{L,macro}})}{\sqrt{(h_{\mathrm{L,full}} \mid h_{\mathrm{L,full}})(h_{\mathrm{L,macro}} \mid h_{\mathrm{L,macro}})}}.$$
 (12)

We then define the match $\mathcal{M}[h_{L,\text{macro}}, h_{L,\text{full}}]$ to be the maximum of $\mathcal{O}[h_{L,\text{macro}}, h_{L,\text{full}}]$ over time and phase, and $1 - \mathcal{M}[h_{L,\text{macro}}, h_{L,\text{full}}]$



Figure 8. Contour plot of the effective micro-amplification $\sqrt{\mu_{\rm m}}$ for our lens set-up as a function of the microlens mass *m* and the micro impact parameter $\eta_{\rm m}$. The behaviour of $\sqrt{\mu_{\rm m}}$ almost does not depend on $\eta_{\rm m}$ for a low *m*.



Figure 9. The mismatch between the waveforms with and without microlensing for our lens set-up as a function of the microlens mass *m* and the micro impact parameter $\eta_{\rm m}$. The contour lines of mismatch $\in \{0.1, 0.5, 1.0\}$ per cent are shown. Stellar mass microlenses of $m \leq 10 \,\rm M_{\odot}$ have a mismatch in the subpercent level.

to be the microlens-induced mismatch. The match is also computed using the PYCBC software (Nitz et al. 2020).

Fig. 9 shows a contour plot of the mismatch 1 - $\mathcal{M}[h_{L,macro}, h_{L,full}]$ between the waveforms with and without microlensing as a function of m and η_m . For most of the parameter space concerned, the mismatch ≤ 1 per cent except for $m, \eta_{\rm m} \sim$ $100 \,\mathrm{M_{\odot}}, 0.1 \,\theta_{\mathrm{m}}$. For $m \lesssim 10 \,\mathrm{M_{\odot}}$, the mismatch $\lesssim 0.5$ per cent. We note that the waveform's mismatch does not encode any information about the macroimage magnification μ , which scales the signal-tonoise ratio of the signal as $\sqrt{\mu}$. However, as the mismatch is at the subpercent level for typical stellar masses of $m \lesssim 10 \,\mathrm{M}_{\odot}$, it is expected that microlenses would not significantly affect the measurement of other GW parameters for typical magnifications $\mu \leq 10$. We note that more complicated scenarios with a field of microlenses still exist and there are some rare cases when we could observe extremely large macromodel magnifications ($\mu \sim 100$). These scenarios may still induce more substantial stellar microlensing features on the waveform (Diego et al. 2019; Diego 2020).

With the same macromodel set-up, we also vary the direction we place the microlenses from the macroimage, with $\phi_m \in \{45^\circ, 90^\circ,$



Figure 10. Varying the angular direction with respect to the macroimage for which we place the microlens. The SIS centre is to the left of the figure and ϕ_m is the angle between the microlens and the SIS centre measured at the macroimage. The dashed and solid circles correspond to $\phi_m \in \{0^\circ, 45^\circ, 90^\circ, 135^\circ, 180^\circ\}$.

135°, 180°}, where ϕ_m is the relative angle from the SIS centre to the microlens measured at the macroimage as shown in Fig. 10. The cases examined previously corresponds to $\phi_m = 0^\circ$, while the results for the range 180° $< \phi_m < 360^\circ$ are similar to those examined here by symmetry of the model. The deviation in micro magnification and the mismatch for the above cases are plotted in Fig. 11, showing that the microlens displacement relative to the macroimage does not affect the results significantly for $m \lesssim 10 \,\mathrm{M_{\odot}}$.

Although microlensing due to a single star might not affect GWs significantly, we are interested in the case of GW microlensing by multiple stars as well. Following Christian et al. (2018), we also study the case of the GW passing through the Einstein ring of two microlenses, which is rare but possible when the lens galaxy has a high stellar density. We use the same $10^{10} \, M_{\odot}$ SIS macromodel as that in the main text, and restrict ourselves to the minimum macroimage. We draw two masses m_1 and m_2 from the Chabrier (2005) mass function (Chabrier 2005) as implemented in the IMF package (Ginsburg 2021). Then, we place m_1 at a random position within a disc of radius θ_{ml} centred at the macroimage position, and we repeat such procedure with m_2 and θ_{m_2} (thus lenses with smaller masses are generally placed closer to the macroimage). We simulate 1000 of these microlens pairs, calculate the amplification factor for each configuration, and compute the micro magnification factor as in equation (10) and the microlens induced mismatch as in Fig. 9. The results are shown in Fig. 12. The results give $\sqrt{\mu_m} < 1.062$ or mismatch < 0.135 per cent, respectively, for 95 per cent of the simulations. The outliers to even higher $\sqrt{\mu_{\rm m}}$ or mismatch correspond to the unlikely cases of heavy stars ($m \gtrsim 10 \,\mathrm{M}_{\odot}$) present near the macroimage. It should be noted that the macroimage position is within the Einstein radius of both m_1 and m_2 in our simulations, but it is more probable that only one (or none) of the masses would be that close to the macroimage. Therefore, single or double stellar microlensing would typically not affect the GW signal.

4 DISCUSSION

4.1 Implications of waveform suppression

In most micro- and millilensing situations above 100 M_{\odot} , the geometrical optics limit describes the physical configuration well at the most sensitive LIGO/Virgo frequencies. However, for microlenses



Figure 11. Micro amplification factor μ_m (left column) and mismatch (right column) for $\phi_m \in \{45^\circ, 90^\circ, 135^\circ, 180^\circ\}$ (from top to bottom). For $m \leq 10 M_{\odot}$, the features are qualitatively similar to those in the case discussed in the main text (see Figs 8 and 9). For $m \geq 10$, varying ϕ_m does introduce some differences, meaning that the ability to detect microlenses in this higher mass range would at least depend on the three parameters m, η_m , and ϕ_m .

below 100 M_{\odot} , wave diffraction effects become non-negligible. Wave optics effects suppress the lensing magnification due to microlenses, especially in common astrophysical strong lensing scenarios with microlenses $\sim 1 \text{ M}_{\odot}$, and even for the case of two of such microlenses present near to the GW trajectory. We note that there are still even rarer astrophysical situations where more microlenses could plausibly conspire together to mimic larger lenses (Diego et al. 2019; Diego 2020), but our results are nevertheless promising, and may have exciting implications for studies of fundamental physics and cosmology through localization studies.

In particular, as pointed out by Oguri (2019), typical microlensing may significantly and adversely affect the accuracy and precision of time delay and magnification measurements of lensing transients. As the typical radii of the objects emitting GWs are small (the orbital radius of binary compact object mergers can be as low as $R \sim 10$ km), GWs can in principle be subject to considerable



Figure 12. The effective micro amplification $\sqrt{\mu_{\rm m}}$ and microlens induced mismatch for the 1000 simulated double microlens configurations. The masses of the two stars are drawn from an initial mass function. The 95th percentile of $\sqrt{\mu_{\rm m}}$ is 1.062, while that of the mismatch is 0.135 per cent.

microlensing in the usual geometrical optics limit (Oguri 2019). However, our results confirm that the wave optics effects suppress stellar microlensing (see also discussion on isolated lenses in Oguri 2019). This suggests that GWs may allow for relatively clean measurements where we need to worry less about microlensing systematics in, e.g. localization studies (Hannuksela et al. 2020) and possible follow-up studies thereafter (Sereno et al. 2011; Baker & Trodden 2017; Collett & Bacon 2017; Fan et al. 2017; Liao et al. 2017; Cao et al. 2019; Li et al. 2019b; Hannuksela et al. 2020). Indeed, for example, the lensed GWs may be a promising means for us to constrain cosmological parameters, such as the Hubble constant H_0 , by accurately measuring the time delay of different strongly lensed GW images. Intriguingly, GWs are not as vulnerable to microlensing as the EM waves from supernovae and other explosive transients (see discussion in Oguri 2019). Systematic errors due to microlensing can potentially play a significant role in these measurements. Thus, wave optics suppression can be seen as an advantage in this case.

Moreover, quadruply lensed GWs could be used to localize the host galaxy of lensed waves by matching the GW image properties with the lensed galaxy systems found in the direction of the GW in an EM follow-up (Hannuksela et al. 2020). Microlensing could induce a significant error on the lensing time delay and magnification, hampering the match between the image properties (magnifications, time delays) found in the EM and the GW channels. Our work suggests that these localization studies may suffer from stellar microlensing in the common astrophysical scenarios to a much lesser degree, which may spell improvements for these localization studies. Subsequently, microlensing may pose less of a problem in measuring H_0 through methods based on the distance-ladder or the time-delay distance. Additional work is still needed to investigate more complex microlensing scenarios, such as fields of microlenses near the saddle point macroimage (type-II image). Nevertheless, our results are very promising.

Finally, our results illustrate the mass ranges for which wave optics effect becomes significant. As shown in Fig. 5, both the magnitude and argument of the amplification factor deviate significantly from the geometric optics model even at a microlens mass of $30 \, M_{\odot}$. In Appendix A, we show that the validity of the geometrical optics approximation depends at least on the mass of the lens and the frequency range in question, and the approximation might be good enough for LIGO detections for microlenses of mass $m \gtrsim 300 \, M_{\odot}$.

4.2 Non-minimum macroimages

In this paper, we focused on the amplification factors of microlenses near the macromodel minimum point (a type-I image) of the time delay function. This is for computational simplicity, as only the area immediately surrounding the minimum contributes to the diffraction integral around the macroimage time delay.

However, for a type-II images (saddle points), the regions of the lens plane with time delay $t_d(\vec{\xi}, \vec{\eta}) \in [t_{im} - \tau, t_{im} + \tau]$ correspond to thin strips centring around the contour lines $t_d(\vec{\xi}, \vec{\eta}) = t_{im}$. As the macroimage is a saddle point, such a contour line can have an arbitrary length that depends on the lens model. In SIS lensing with typical galactic masses, the relevant contours at the saddle point will be vast, making the calculation of equation (6) very computationally expensive. It has been shown in Diego et al. (2019) that microlensing around type-II images have qualitative differences from that around type-I ones. We will develop methods to tackle type-II images of general lens configurations in future work.

5 CONCLUSIONS

We have shown that a wave optics treatment of the full lens model is required for stellar-mass microlensing on a galactic macromodel. Due to diffraction effects, microlensing is suppressed, making the contributions by stellar lenses of mass $\sim 1 \, M_{\odot}$ small regardless of their proximity to the macrolensed GW beams. This allows for more accurate measurements of the magnification and time delay of lensed GW images and better confidence in localization studies. On the flip side, we might require third-generation detectors to use GW lensing to probe objects of masses $\mathcal{O}(1 \, M_{\odot})$. Future work will include the cases of microlensing near type-II macroimages.

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DATA AVAILABILITY

The data underlying this article will be shared on reasonable request to the corresponding authors.

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APPENDIX A: ACCURACY OF THE GEOMETRICAL OPTICS APPROXIMATION

It has generally been accepted that the geometrical optics limit approximates the exact results better for higher frequencies f and higher (micro)lens masses m. In Fig. A1, we compare the full wave optics calculation (the solid lines) and geometrical optics approximate (the dashed lines) of the amplification factor F for the set-up in Fig. 3 but with $m = 100 \,\mathrm{M}_{\odot}$. Comparing Figs 4 and A1, we see that the geometrical optics approximation approaches the wave optics calculations at a lower frequency for the more massive case $m = 100 \,\mathrm{M}_{\odot}$. More explicitly, we can quantify the error of the geometrical optics limit by taking the norm of the



Figure A1. Same as Fig. 4, but with a microlens mass of $m = 100 \,\mathrm{M_{\odot}}$ instead. There is still a clear mismatch between the geometrical and wave optics limits for $f \lesssim 10^2 \,\mathrm{Hz}$.



Figure A2. Deviation between the wave optics and geometrical optics results of the amplification factor for $m \in \{1, 30, 100, 300, 500\} M_{\odot}$. The shaded region corresponds to $|F_{wave} - F_{geom}|/\sqrt{\mu} < 0.1$. The curves for $m \in \{300, 500\} M_{\odot}$ lie within this region for the most sensitive frequency range $f \sim \mathcal{O}(10^2 \text{ Hz})$ of LIGO.

difference between the wave optics amplification factor F_{wave} and the geometrical optics amplification factor F_{geom} . In Fig. A2 we plot the results for $m \in \{1, 30, 100, 300, 500\} M_{\odot}$ (normalized by $\sqrt{\mu}$). For $m \in \{300, 500\} M_{\odot}$, the normalized error in the geometrical optics approximation is <0.1 for most of the frequency range sensitive for LIGO, meaning that the approximation might be good enough for $m \gtrsim 300 M_{\odot}$ depending on the accuracy required.

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