

# Inter-System Time Lag due to Clouds in an Urban PV Ensemble

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### CONTEXT

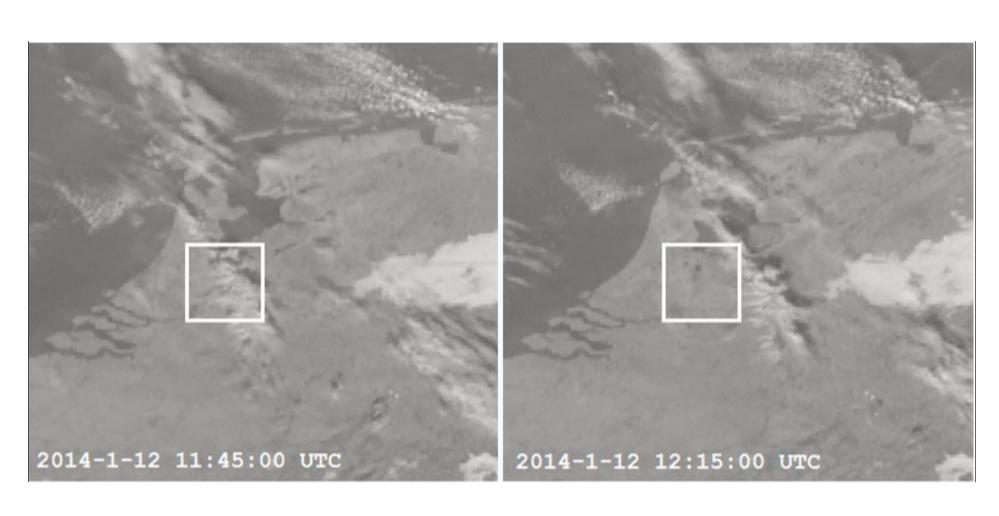
- In situ determination of cloud transit **time** lag on reconstructed Global Horizontal Irradiance (GHI) and the use of this time lag for short-term irradiance **forecasting**.
- Part of project: Solar Forecasting & Smart Grids: aimed at improving the hosting capacity for PV in the Dutch LV/MV grid.

## **SET UP**

- 177 small residential Rooftop PV-systems (< 5 kWp) in and around the city of Utrecht (The Netherlands) covering approx. 1600 km<sup>2</sup>.
- High resolution Energy and Power measurements with Wi-Fi link (AC side).
- Power Output measurements of 0,7 W and 2 sec resolution; 5 sec. interpolation used for GHI reconstruction.

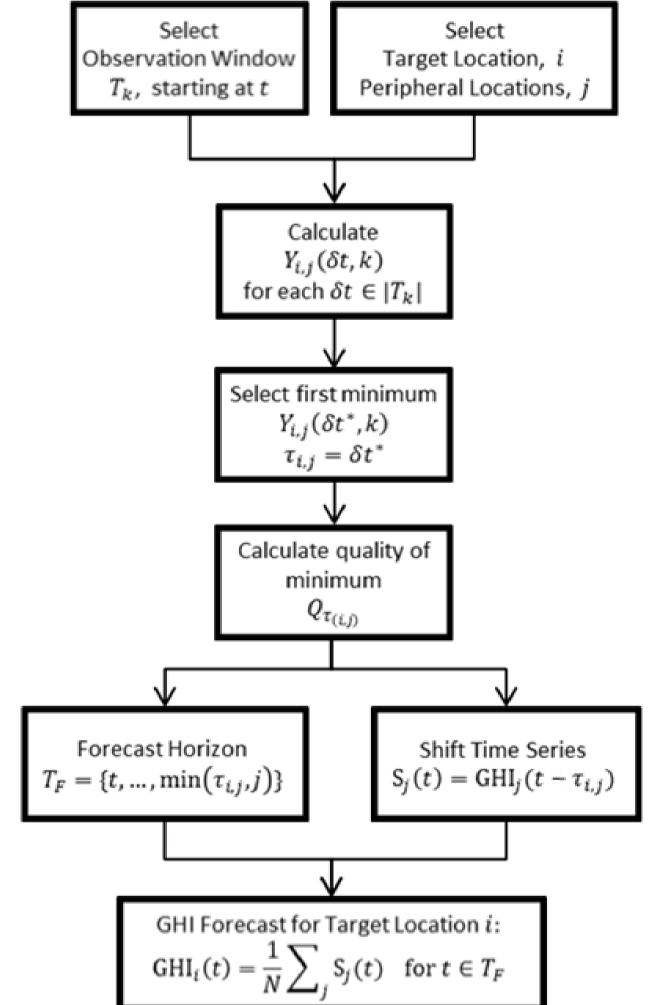
## **METHOD**

- Relative **shift** ( $\delta t$ ) of GHI(t) (or  $\Delta$ GHI(t)) time series of two PV-system locations.
- Calculation of overlap  $Y(\delta t)$  of time series within a fixed **observation window** (e.g. 15 min.).
- Minimization of **overlap** gives **time lag**  $\tau$  of passing cloud for these two locations.



#### FORECASTING ALGORITHM

• Data from **several** peripheral PV-system locations *j* combined, are shifted by their respective time lag to **forecast** the GHI and thus Power at a location *i*.



Relative shift  $\delta t$  [min.]

#### Irradiance time series at two locations **Overlap function vs Relative shift** $15) [\mathrm{Wm}^{-2} \mathrm{s}]$ 15 000 300 $[\mathrm{Wm}^{-2}]$ 10 000 $Y_{i,j}(\delta t,\mathbf{k}:$ Relative shift of $GHI_i(t)$ Time lag $\tau \approx$ 2:20 min. by $\delta t$ 100 5000 @ minimum overlap Observation a Window 14 11:30 12:00 12:15 12:30 11:45 Relative shift $\delta t$ [min.] Time [h] **Irradiance Fluctuation time series at two locations Overlap function vs Relative shift** 8000 $Y^{\Delta}_{i,j}(\delta t,k=15)$ [Wm<sup>-2</sup>] $\mathbf{s}^{-1}$ 6000 $^{-2}(5$ ∆GHI [Wm 4000 Time lag $\tau \approx$ 2:20 min. @ minimum overlap Relative shift of $\Delta GHI_i(t)$ 2000 Observation d C Window

Figure shows GHI(t) time series (a) and shifted overlap function (b). Similarly  $\Delta$ GHI(t) time series (c) and corresponding overlap function (d). The two locations of interest are separated approximately 3.2 km and both methods produce the same time lag of 2:20 min. Noteworthy, the  $\Delta$ GHI(t) method (c and d) produces a much more distinctive minimum.

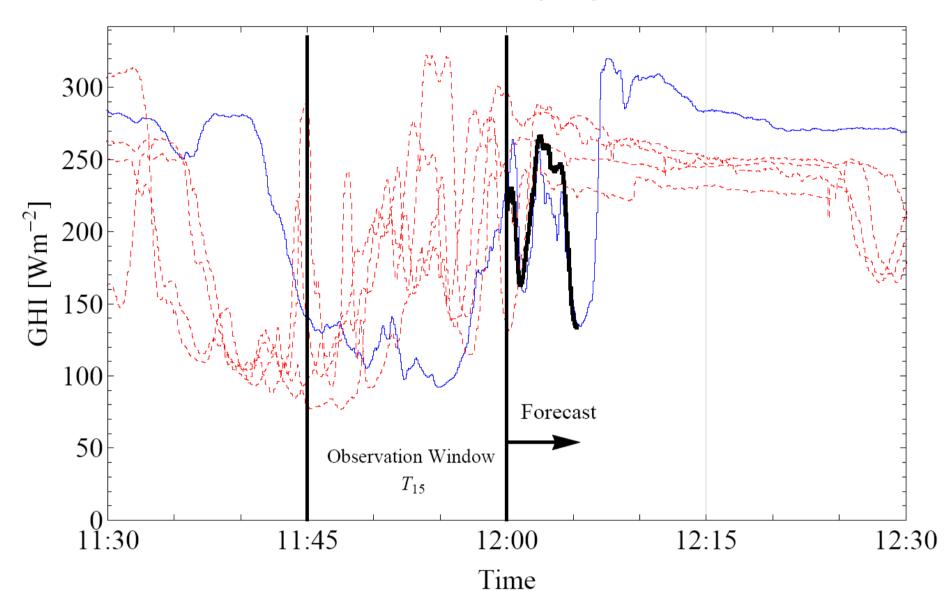
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#### **RESULTS**

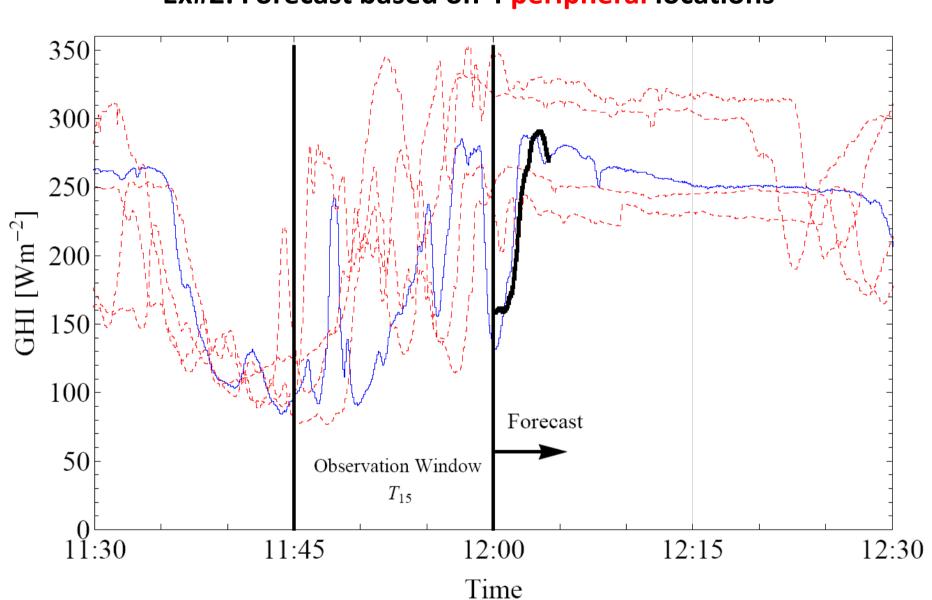
• GHI(t) time series of four peripheral PV-system locations (red, dashed) shifted by their respective time lag combined, produce the forecast (solid thick line) for the target location (solid blue line). This forecast can be compared with the actual development of the GHI(t) of the target location.

Two examples are presented below:

Ex#1: Forecast based on 4 peripheral locations



Ex#2: Forecast based on 4 peripheral locations



## FURTHER RESEARCH

- Numerical validation of the forecast
- Optimize selection of peripheral locations
- Updating forecast every minute (moving observation window) and using e.g.
   Kalman Filtering.
- Determination of time lag itself not very sensitive to relative normalization, but forecast of GHI(t) requires reliable meta data of PV systems.

## SUMMARY / CONCLUSION

- Reliable determination of time lag
- No external meteorological data needed.
- Straight forward forecasting method: no "Black box" methods as e.g. Artificial Neural Networks.

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Time [h]

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